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Systems for Diagnosis and Treatment of Breast Cancer

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Dean Katsaros, Terry Mullen, Sam Nguyen, Oliver
Spiro, Melissa Sych**

University of Massachusetts Amherst

February 26, 2018



Outline

- 1** Introduction
- 2** Anomaly Detection
- 3** Classification
 - Classical ML
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- 4** Tumor Growth and Treatment
- 5** Conclusions
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Motivation

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- 39.6 percent of men and women in the US will be diagnosed with cancer at some point during their lifetimes
- One in eight women in the US will be diagnosed with breast cancer
- Early detection is essential in treatment
- Computer Automated Detection and Diagnosis is currently used as "second reader" to the radiologist to make sure no detection is missed



Our Goals

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- Detect abnormal regions in a mammogram
- Classify those regions as malignant or benign
- Understand and implement tumor development models that account for competing cell populations and chemotherapy



Detection System Goal

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- The goal of our group was to research and further develop algorithms to identify the presence of a mass in a mammogram
- Can we identify the same masses that radiologist do? Can we do better?



The Data Used

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- Public data base from the Cancer Imaging Archive called the Curated Breast Imaging Subset of DDSM (CBIS-DDSM)
- For each patient we had full mammogram and mass mask images as well information on the type of mass identified



One Case

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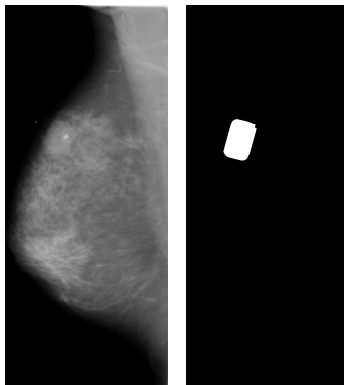


Figure: Patient 100, Benign Mass



Challenges and Solutions

- Mass characteristics (shape, size, density) differ for each patient
- The tissue in the background has similar characteristics to masses
- Mammogram images are from 1990s and not digital so they have poor contrast/quality
- In order to improve image quality and identify masses we will use a three step process:
 - 1** Apply a linear transformation enhancement filter
 - 2** Segment mass regions
 - 3** Use adaptive thresholding for mass identification

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Image Enhancement Filter

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$$El_{ij} = \begin{cases} a \log(1 + bOl_{ij}) & Ol_{ij} < \alpha \\ \frac{\exp\left(\frac{Ol_{ij}}{a} - 1\right)}{b} & Ol_{ij} > \alpha \end{cases}$$

- Ol = original image
- El = enhanced image
- m is the maximum value of the gray level in the image
- a and α are parameters to be chosen empirically

- $b = \frac{1 - \exp\left(\frac{m}{a}\right)}{m}$



Why does it work?

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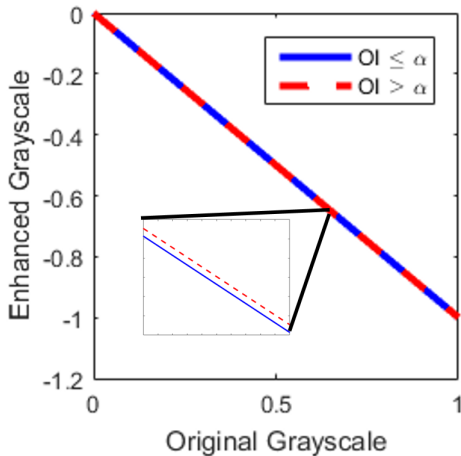
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Result

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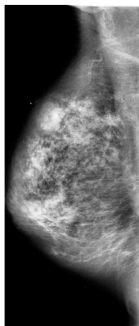
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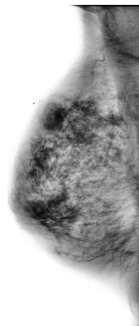
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(a) Original mammogram



(b) Enhanced mammogram



Segmentation of Mass Regions

Segment the regions of interest by:

$$SI = OI + EI$$

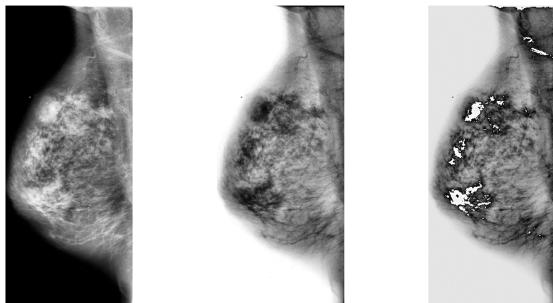


Figure: The full (left), enhanced (middle), and segmented (right) mammograms.

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Near the Mass

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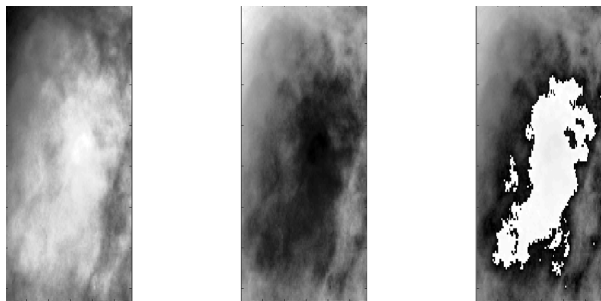


Figure: Original (left), enhanced (middle), and segmented (right) mammograms



Adaptive Local Thresholding

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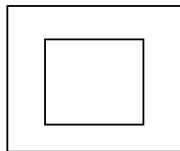
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- Create an adaptive threshold

$$TH_{ij} = M_{ij} + \gamma SI_{diff\ ij},$$



- $SI_{diff\ ij} = SI_{max\ ij} - SI_{min\ ij}$ from large window
- M_{ij} = mean intensity in small window
- γ to be set empirically between 0 and 1
- If $SI_{ij} \geq TH_{ij}$ and $SI_{ij} \geq M_{ij}$, then the pixel is suspicious



Why adaptive?

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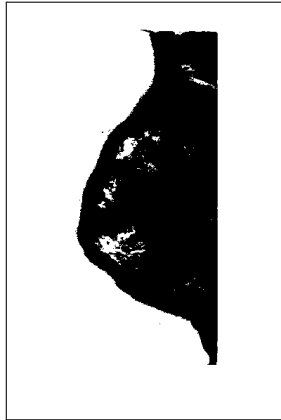


Figure: The resulting mask when we threshold every pixel with the same threshold



Results

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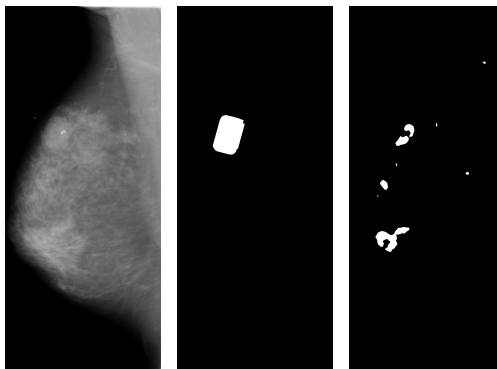


Figure: Original mammogram (left), the mask given by the data set (center), and the mask found by adaptive thresholding (right)



Classification

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- Goal: Classify possible masses as benign or malignant
 - 1 Use hand crafted features to classify
 - 2 Use deep neural networks to learn features to classify
- Let \mathbf{x} be a feature obtained from the mammogram and $y \in \{-1, 1\}$ be the label -1 if the mass is benign and 1 if the mass is malignant.
- A classifier is a function f that takes in \mathbf{x} and outputs y



Histogram of Oriented Gradients

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- Let I be the image
- At each pixel compute:
 - 1 Gradients: I_x and I_y
 - 2 Orientation: $\theta = \tan^{-1}\left(\frac{I_y}{I_x}\right)$
 - 3 Magnitude: $\sqrt{I_x^2 + I_y^2}$
- Partition image into blocks
- For each block take weighted histogram of orientations weighted by the gradient magnitude



HOG Features

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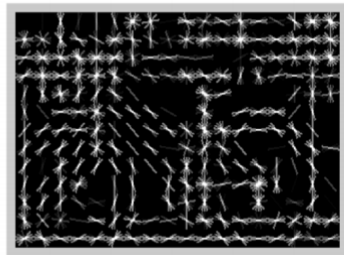


Figure: A visualization of the HOG features



Classifiers

Logistic Regression:

$$y^* = \arg \max_y P(y|\mathbf{w}, \mathbf{b}, \mathbf{x}) = (1 + e^{\mathbf{w}^T \mathbf{x} + b})^{-1}$$

Support Vector Machines:

$$y^* = \text{sign}(\mathbf{w}^T \mathbf{x} + b)$$

- y^* : label found by classifier
- \mathbf{w} : weight vector
- b bias:

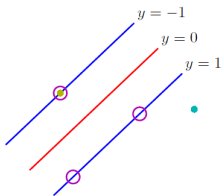


Figure: SVM maximized the margin and finds the optimal separating hyperplane between classes ¹.

¹Bishop, Christopher, "Pattern Recognition and Machine Learning"



Some Classification Results

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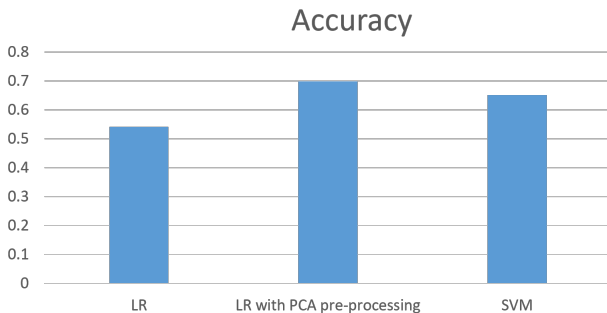


Figure: Classification accuracy for using the HOG features. The best performing HOG parameters were a block size of 32 and 11 angle bins (LR), block size of 32 and 14 angle bins (LR with PCA pre-processing), and block size of 32 and 15 angle bins (SVM).



Neural Nets

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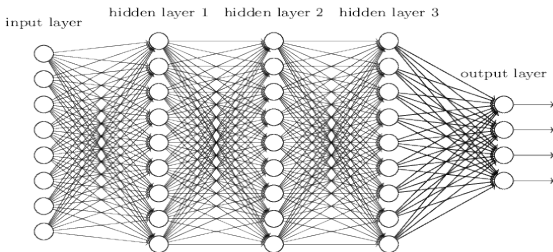
The goal of our classification is to fit an approximation f to the true classifier function

$$f^* : \mathcal{M} \rightarrow \{-1, 1\}$$

Where $\mathcal{M} \subset [0, 1]^{w \times h}$ is the space of mammogram images, and the labels $\{-1, 1\}$ represent the diagnosis



- Build this classifier from small parts
- The approximator $f(\mathbf{x})$ is the composition of multiple functions referred to as **layers**
- Each individual layer consists of simple functions known as **units**²



²Also called neurons.



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Each unit $g : \mathbb{R}^m \rightarrow \mathbb{R}$ is parametrized by a *weight vector* \mathbf{w} and a scalar *bias* \mathbf{b} Typically:

$$g(\mathbf{x}; \mathbf{w}, b) = h(\mathbf{w}^T \mathbf{x} + b)$$

- h is a fixed nonlinear function called an **activation**
 - Usually $h(z) = \max\{0, z\}$ or $h(z) = 1/(1 + e^{-z})$
- \mathbf{w} and b are fit to the training data



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A **Layer** $f^{(i)}$ is then a vector of a number of units stacked together

$$f^{(i)}(\mathbf{x}) = [g_1^{(i)}(\mathbf{x}), g_2^{(i)}(\mathbf{x}), \dots, g_d^{(i)}(\mathbf{x})]^T$$

Finally, we combine these layers via nested composition. If \mathbf{x} comes from the set of input images, we have

$$f^{(i)}(\mathbf{x}) = f^{(i)}(f^{(i-1)}(\dots(f^{(1)}(\mathbf{x}))))$$

This is our **Network**



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Recall that our goal is to find an f that approximates the true classifier

$$f^* : \mathcal{M} \rightarrow \{-1, 1\}$$

- Normalize the output of the final layer to give a probability distribution
- f is the function that returns -1 or 1 based on which class has higher probability



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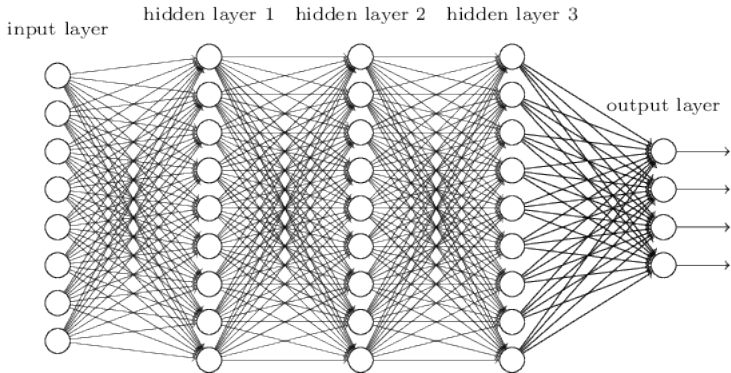
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Training/Fitting

Now we have the functional form of the function f used for prediction, but how do we find a good set of parameters?

- Supervised learning: Give the network pairs (\mathbf{x}, \mathbf{y}) , where $\mathbf{y} \in \{-1, 1\}$ is the diagnosis
- compute a **Loss** function to quantify the “badness” of fit
- Similar to likelihood maximization used in linear regression, etc.
- Minimize loss using gradient descent and **Backpropagation** to fit weights and biases to the data

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Convolutional Neural Networks

- As is common practice with image data, we actually used **Convolutional** neural networks
- The functional form differs subtly in these networks, using a (discrete) convolution instead of an inner product in the unit functions

We now retain the 2D structure of each x , and then the convolution maps it to another 2D grid of units, with entries:

$$g_{mn}(\mathbf{x}; \mathbf{w}, b) = h \left((\mathbf{w} * \mathbf{x})_{mn} + b \right)$$

$$(\mathbf{w} * \mathbf{x})_{mn} = \sum_{k,l} w_{m+k,n+l} \cdot x_{kl}$$

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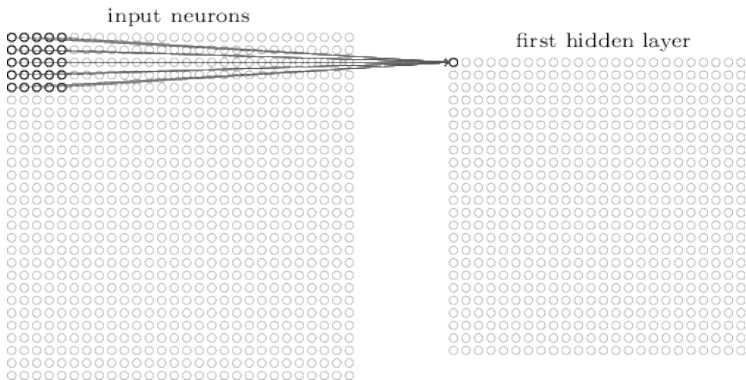
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- Neural networks with numerous layers are referred to as “deep”
- One of the crippling drawbacks of such networks is the sheer volume of training data they need
- Results that make headlines with their near perfect accuracy can use upwards of a million training images



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- We had ≈ 1200 mammography images
- In many applications gathering more data may not be feasible nor ethical (e.g medical data)
- We can take advantage of networks pretrained on tasks where data is abundant



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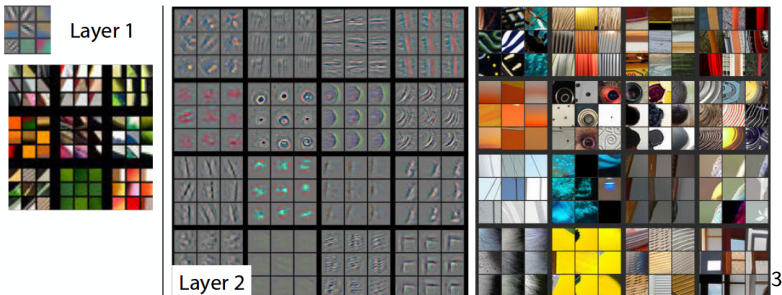
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³From Zeiler and Fergus



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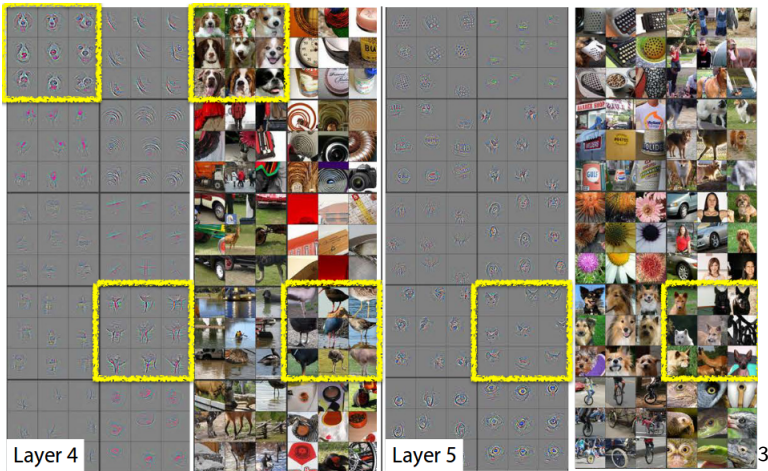
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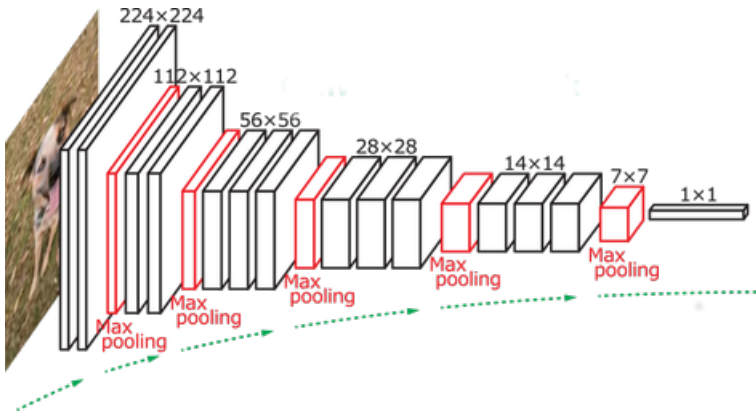
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Data Augmentation

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- Artificially generates new data
- Addresses lack of data by increasing effective sample size
- Guards against overfitting to the training set
- Our augmentation included:
 - reflecting images horizontally
 - reflecting vertically
 - small-scale zooms



Architectures

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Baseline convolutional network:

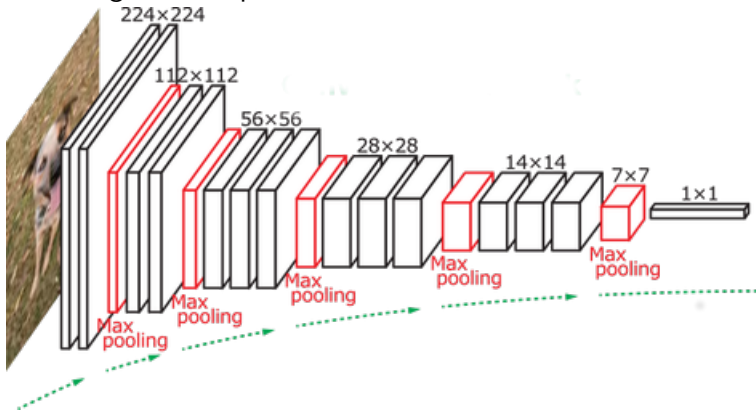
- Trained only on our data
- 3 convolutional layers plus 2 fully connected layers
- Used as proof of concept



Architectures

VGG 16:

- 16 layers deep
- Performed exceptionally well for its simplicity in the 2014 ImageNet competition



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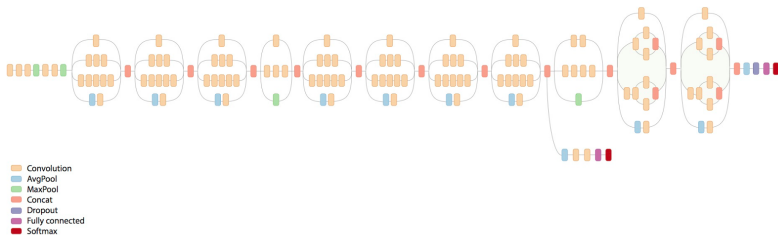
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GoogLeNet (Inception):

- 22 layers deep
- Introduced inception module
- Won ImageNet competition in 2014
- We used inception V3





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- All neural networks implemented in Keras with a Tensorflow backend
- All GPU intensive computations run on Amazon Web Services (Many thanks to Prof. Hajir and the department)
 - p2.xlarge GPU instances
 - Training time: 1-2 days



Baseline

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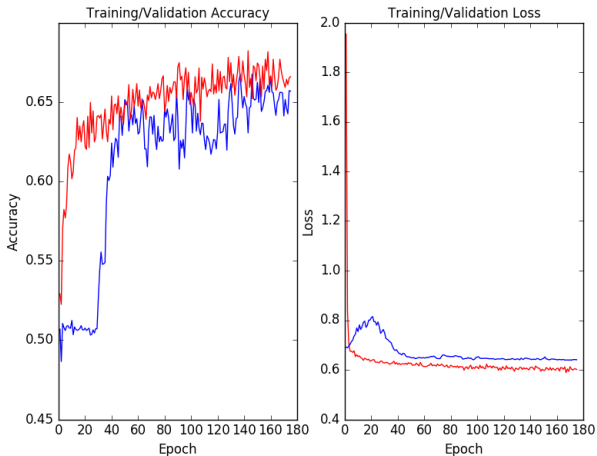
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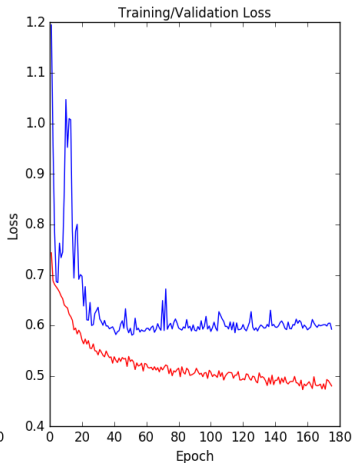
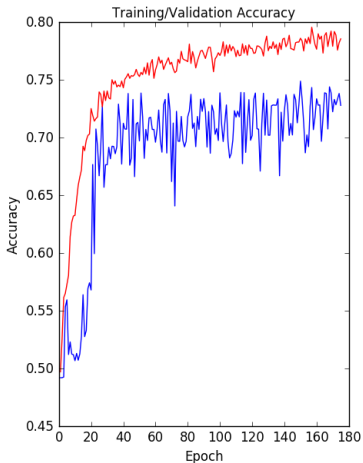
Training (red) and Validation (blue) Accuracy / losses for Baseline Network





VGG 16

Training (red) and Validation (blue) Accuracy / losses for Transfer Learning on VGG16 Network



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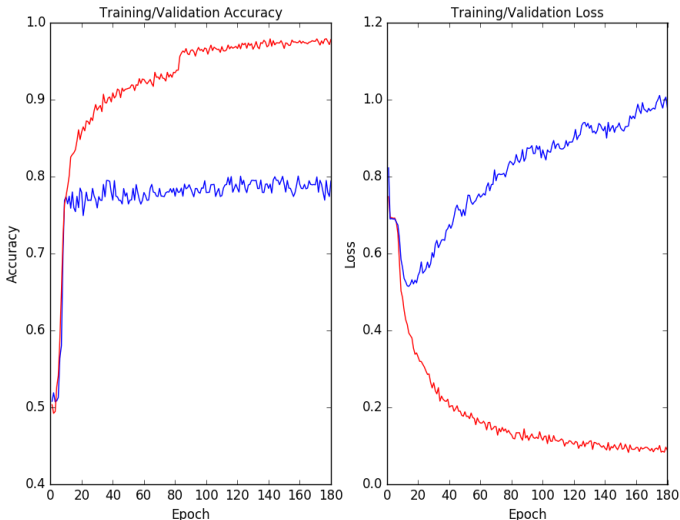
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Inception V3

Training (red) and Validation (blue) Accuracy / losses for Transfer Learning on Inception V3



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After 180 epochs:

- Baseline: 65%
- VGG-16: 72%
- GoogLeNet (Inception V3): 78%
- Best in literature: 92%



Modeling Cell Populations

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- Want to understand how tumors grow
- Over the years scientists and mathematicians have attempted to model tumor growth
- Our model describes the interaction between the host, effector, and tumor cells



Competing Cells

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1. HOST CELLS

2. A CANCER CELL BEGINS



3. CANCER CELLS MULTIPLY

4. EFFECTOR CELLS
(T-CELLS & NK CELLS)
ATTACK



Figure: How Cells interact



System of ODE's

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$$\dot{T} = r_1 T \left(1 - \frac{T}{K_1}\right) - a_{12} HT - D(E, T) T$$

$$\dot{H} = r_2 H \left(1 - \frac{H}{K_2}\right) - a_{21} HT$$

$$\dot{E} = \sigma - d_3 E + g \frac{D^2(E, T) T^2}{h + D^2(E, T) T^2} E - a_{31} TE$$

$$D(E, T) = d \frac{E^\lambda}{sT^\lambda + E^\lambda}$$

- T - tumor cells, H - host cells, E - effector cells
- a - competition terms
- r - individual growth constants
- K - carrying capacity



Nondimensionalized Equations

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$$\dot{x} = x(1 - x) - a_{12}yx - D(x, z)x$$

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$$\dot{y} = r_2y(1 - y) - a_{21}xy$$

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$$\dot{z} = 1 - d_3z + g \frac{D^2(x, z)x^2}{h + D^2(x, z)x^2}z - a_{31}xz$$

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$$D(x, z) = d \frac{f^\lambda z^\lambda}{sx^\lambda + f^\lambda z^\lambda}$$

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- x - tumor cells
- y - host cells
- z - effector cells

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Stable Fixed Points

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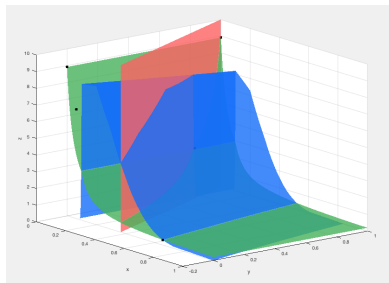


Figure: Graph of nullclines and stable fixed points

- Obtain fixed points by setting $\dot{x} = \dot{y} = \dot{z} = 0$
- $x_1^* = (0, 1, 8.93)$
- $x_2^* = (0.65, 0, 0.31)$
- $x_3^* = (0.06, 0, 6.55)$



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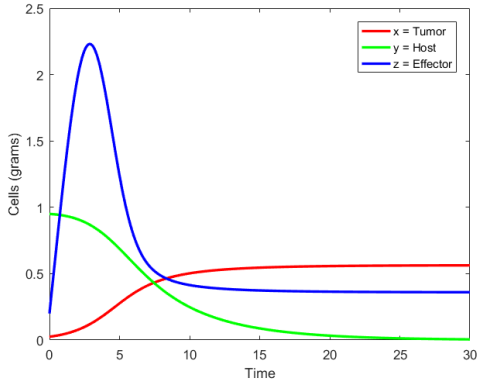


Figure: A function of each cell population over time



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- Need to test the model with other data
- Hiramoto and Ghanta (1974)
 - 36-Day Experiment
 - Day 0: Injected mice with tumor cells
 - Day 10: Cell populations start to change
 - Record cell populations at Days 10,18,21



Process

- Given the data, fit coefficients to approximate the data
- Some coefficients found experimentally
- Use Least Squares to find the others
- We fit d , s , and g
- Solve for x , y , z using RK4

$$\dot{x} = x(1 - x) - a_{12}yx - D(x, z)x$$

$$\dot{y} = r_2y(1 - y) - a_{21}xy$$

$$\dot{z} = 1 - d_3z + g \frac{D^2(x, z)x^2}{h + D^2(x, z)x^2}z - a_{31}xz$$

$$D(x, z) = d \frac{f^\lambda z^\lambda}{sx^\lambda + f^\lambda z^\lambda}$$

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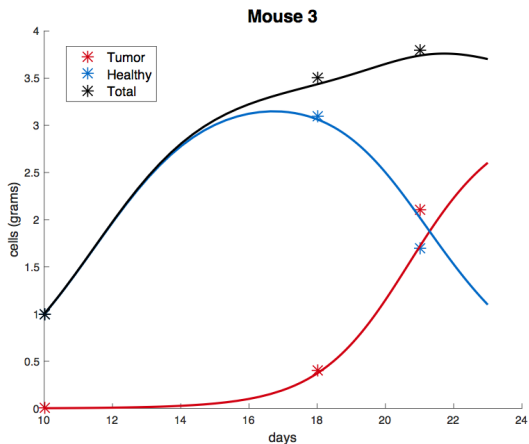


Figure: A function of tumor and healthy cells over time, for Days 10, 18, and 21



Fit of the Data [cont'd]

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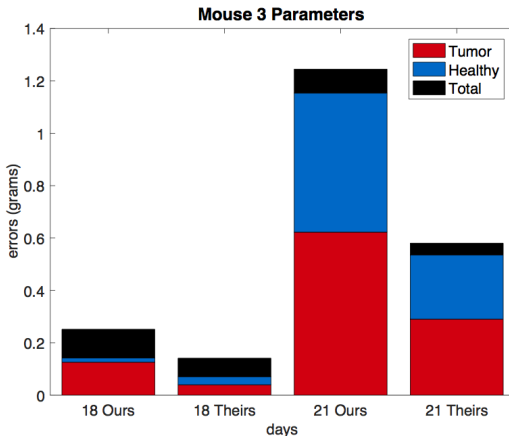


Figure: Residuals of our estimated parameters



Chemotherapy

- After Day 21, inject mice with chemotherapy drug
 - Record populations at Days 24, 27, 30, 33, 36
- Implications for the Model
 - Chemotherapy targets cancer AND healthy cells
 - However, Hiramoto and Ghanta recorded tumor cell data
 - So for simplicity, only note the effects of chemotherapy on tumor cells
 - Body takes some time to realize what the drug is

$$\dot{x} = x(1 - x) - a_{12}yx - D(x, z)x - (1 - e^{-pu(t-\tau)_+})x$$

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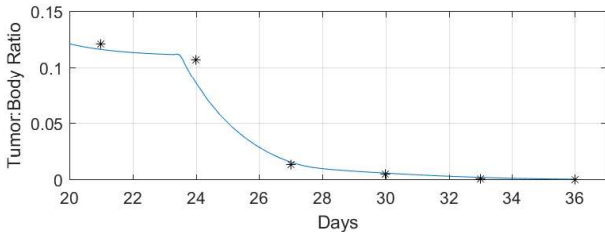
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After Chemotherapy

Figure: Effects of chemotherapy on tumor population.



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Future Work

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■ Mass Detection and Classification

- 1 Using newer digital images should improve performance.
- 2 Need images from a patient over time to better mimic the true detection process
- 3 Explore different neural network architectures
- 4 Report metrics like precision and recall
- 5 Increase interpretability using new techniques

■ Tumor Growth and Treatment

- 1 Repeat procedure with a newer data set
- 2 Observe tumor cells in breast tissue instead of mice
- 3 Analyze effects of chemotherapy on healthy cells



Thank You!

Thank you to Professor Whitaker, Dr. Joseph Polino, Professor Hajir, and everybody in the department.



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We will now take questions.



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